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# A classification of special points of icosahedral quasilattices 

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#### Abstract

We investigate special points of icosahedral quasilattices in three dimensions (3D). They are given as the projections onto the real space of the special points of icosahedral lattices which are periodic lattices in 6D. There exist three Bravais classes of 6 D icosahedral lattices and we present a complete classification of their special points.


## 1. Introduction

We have investigated in the preceding paper (Niizeki 1989b) special points of quasilattices in two dimensions (2D). The quasilattices are obtained by the cut-and-projection method (Janssen 1986, Niizeki 1988a) from 4D periodic lattices, i.e. octagonal, decagonal and dodecagonal lattices, and the special points of the quasilattices are obtained with the same method from those of the starting periodic lattices. We have presented a complete classification of the special points of these periodic lattices. The results are applied to classifications of local and global point symmetries of the relevant 2D quasilattices.

On the other hand, we have shown in Niizeki and Akamatsu (1989) (to be referred to as I) that the special points in the reciprocal space of a 3 D icosahedral quasilattice (IQL) are useful in understanding the properties of the electronic wavefunctions in the 'plane-wave representation'; the quasi-dispersion relation of electron in the IQL is stationary at the special points as in the case of a periodic lattice.

IQL are obtained generally with the cut-and-projection method from 6D periodic lattices whose point symmetries are isomorphic to $\mathrm{Y}_{h}(\overline{5} \overline{3} \mathrm{~m})$, the full icosahedral point group in 3D (Elser 1986, Janssen 1986, Katz and Duneau 1986). There exist three 6D icosahedral lattices, $P \overline{5} \overline{3} m, F \overline{5} \overline{3} m$ and $I \overline{5} \overline{3} m$, and they give rise to three Bravais classes of IQL (Janssen 1986, Rokhsar et al 1987, Levitov and Rhyner 1988).

The special points of IQL are obtained with the cut-and-projection method from those of the starting lattices in 6D. We have treated only $P \overline{5} \overline{3} m$ in I. We shall restrict our arguments to the cases where the space groups of the 6 D lattices are symmorphic and their point groups are isomorphic to $Y_{h}$.

In § 2, we introduce the three 6D icosahedral lattices and present their relationships to IQL. In § 3, we present a general theory of the special points of a (periodic) Bravais lattice with a symmorphic space group. In § 4, we shall classify the special points of the 6D lattices and, in § 5, discuss related subjects.

## 2. The 6D icosahedral lattices and 3D icosahedral quasilattices derived from them

A regular icosahedron $\mathscr{Y}$ in $E_{3}\left(\simeq \mathbb{R}^{3}\right)$, the 3D Euclidean space, has six fivefold axes, ten threefold axes and fifteen twofold ones, which pass through the vertices, the face
centres and the middle points of the edges, respectively. $\mathscr{Y}$ has inversion symmetry and the full point group of $\mathscr{y}$ is $\mathrm{Y}_{h}$, whose order is $120 ;\left|\mathrm{Y}_{h}\right|=120$.

The twelve vertices of $\mathscr{Y}$ are grouped into six pairs by the inversion symmetry and six of the twelve vertex vectors of $\mathscr{y}$ centred at the origin of $E_{3}$ are linearly independent over $\mathbb{Q}$, the rational field. We choose the cartesian coordinate system so that the three axes are parallel to three twofold axes which are orthogonal to each other. By choosing the size of $\mathscr{y}$ appropriately, we can assume that the six independent vertex vectors are given by $a_{1}=(\tau, 1,0), a_{2}=(0, \tau, 1), a_{3}=(1,0, \tau), a_{4}=(\tau,-1,0), a_{5}=(0, \tau,-1)$ and $\boldsymbol{a}_{6}=(-1,0, \tau)$, where $\tau=(1+\sqrt{5}) / 2$ is the golden ratio. The two vectors, $\boldsymbol{a}_{1}+\boldsymbol{a}_{2}+\boldsymbol{a}_{3}$ and $a_{4}+a_{5}+a_{6}$, are parallel to the threefold axis along (1,1,1) $\equiv[111]$. Note that $\left|\boldsymbol{a}_{i}\right|=\sqrt{\tau+2}$ for all $i$ and $\boldsymbol{a}_{i} \cdot \boldsymbol{a}_{j} /\left(\left|\boldsymbol{a}_{i}\right|\left|\boldsymbol{a}_{j}\right|\right)(i \neq j)$ takes $1 / \sqrt{5}$ or $-1 / \sqrt{5}$. An element of $\mathrm{Y}_{h}$ permutes the $\boldsymbol{a}_{i}$ among themselves and, subsequently, inverts some of them.

The algebraic conjugate of $\tau$ is given by $\tilde{\tau}=(1-\sqrt{5}) / 2(=-1 / \tau)$. Let us define the conjugate vectors to $\boldsymbol{a}_{i}$ by $\tilde{a}_{i}=-\left.\tau \boldsymbol{a}_{i}\right|_{\tau \rightarrow \tilde{\tau}}$. Then, $\tilde{a}_{i}$ are vertex vectors of another icosahedron, $\tilde{\mathscr{Y}}$, which differs from $\mathscr{Y}$ only in its orientation in $E_{3} ; \tilde{\boldsymbol{a}}_{i} \cdot \tilde{\boldsymbol{a}}_{j}=-\boldsymbol{a}_{i} \cdot \boldsymbol{a}_{j}(i \neq j)$. We shall call $\tilde{\mathscr{y}}$ the conjugate of $\mathscr{Y}$.

We can consider, alternatively, that $\tilde{\mathscr{Y}}$ is contained in the conjugate space $\tilde{E}_{3}$ which is another 3D Euclidean space, orthogonal to $E_{3}$. Let $E_{6}=E_{3} \oplus \tilde{E}_{3}$ and $\boldsymbol{\varepsilon}_{i}=\left(\boldsymbol{a}_{i}, \tilde{a}_{i}\right)$, $i=1-6$. Then, we obtain $\varepsilon_{i} \cdot \varepsilon_{j}=a^{2} \delta_{i j}$ with $a=\sqrt{2 \tau+4}$. Therefore, $L_{\mathrm{P}}=$ $\left\{n_{1} \boldsymbol{\varepsilon}_{1}+n_{2} \boldsymbol{\varepsilon}_{2}+\ldots+n_{6} \boldsymbol{\varepsilon}_{6} \mid n_{i} \in \boldsymbol{Z}\right\}$ is a simple hypercubic lattice in 6 D . We shall sometimes denote $\boldsymbol{l}=n_{1} \varepsilon_{1}+\ldots+n_{6} \varepsilon_{6} \in L_{\mathrm{P}}$ as $\boldsymbol{l}=\left[n_{1} n_{2} \ldots n_{6}\right]$ with the $n_{i}$ being the indices of $\boldsymbol{l}$.

The point group of $L_{P}$ is $\Omega(6)$, the ${ }_{6 D}$ hyperoctahedral point group. $\Omega(6)$ is given by a semidirect product of the symmetric group $S(6)$ consisting of all the permutations among the $\boldsymbol{\varepsilon}_{i}$ and an Abelian mirror group generated by the six mirrors, each of which inverts one of the $\varepsilon_{i}$. It follows that $|\Omega(6)|=6!2^{6}=46080$. The maximal subgroup of $\Omega(6)$ among those which leave $E_{3}\left(\subset E_{6}\right)$ invariant is $Y_{h}^{\prime}$, the 6 D icosahedral group, which is isomorphic to $\mathrm{Y}_{h} ; \mathrm{Y}_{h}$ is the restriction of $\mathrm{Y}_{h}^{\prime}$ onto $E_{3}$ and the action of $\sigma^{\prime} \in \mathrm{Y}_{h}^{\prime}$ on $\boldsymbol{\varepsilon}_{i}$ is the same as the action of the corresponding element $\sigma \in \mathrm{Y}_{h}$ on $\boldsymbol{a}_{i}$. The $\boldsymbol{\varepsilon}_{i}$ are basis vectors of a 6D unimodular representation of $\mathrm{Y}_{h}\left(\sim \mathrm{Y}_{h}^{\prime}\right) . \tilde{E}_{3}$ is also an invariant subspace against $\mathrm{Y}_{h}^{\prime} . \tilde{\mathrm{Y}}_{h}$, the restriction of $\mathrm{Y}_{h}^{\prime}$ onto $\tilde{E}_{3}$, is isomorphic to $\mathrm{Y}_{h}$. We shall denote the projectors from $E_{6}$ onto $E_{3}$ (or $\tilde{E}_{3}$ ) by $\pi$ (or $\tilde{\pi}$ ). Then, $\pi\left(\left[n_{1} \ldots n_{6}\right]\right)=$ $n_{1} \boldsymbol{a}_{1}+\ldots+n_{6} \boldsymbol{a}_{6}$ and $\tilde{\pi}\left(\left[n_{1} \ldots n_{6}\right]\right)=n_{1} \tilde{a}_{1}+\ldots+n_{6} \tilde{a}_{6}$.

A 6D periodic lattice is called an icosahedral lattice if its point group is equal to $\mathrm{Y}_{h}^{\prime}$. Though $L_{\mathrm{P}}$ has a larger point symmetry than $\mathrm{Y}_{h}^{\prime}$, we can consider it to be a special icosahedral lattice. A more general icosahedral lattice is formed with basis vectors $\left(a_{i}, c \tilde{a}_{i}\right), i=1-6$, where $c(\neq 0)$ is an arbitary constant.

If $a_{i}$ are scaled up through the ratio $\tau$, the resulting vectors are rationally related to $\boldsymbol{a}_{i}$ as

$$
\begin{align*}
& \tau\left(\boldsymbol{a}_{1}, \boldsymbol{a}_{2}, \ldots, \boldsymbol{a}_{6}\right)=\left(\boldsymbol{a}_{1}, \boldsymbol{a}_{2}, \ldots, \boldsymbol{a}_{6}\right) \mathbf{M}  \tag{1}\\
& \mathbf{M}=\frac{1}{2}\left(\begin{array}{rrrrrr}
1 & 1 & 1 & 1 & 1 & -1 \\
1 & 1 & 1 & -1 & 1 & 1 \\
1 & 1 & 1 & 1 & -1 & 1 \\
1 & -1 & 1 & 1 & -1 & -1 \\
1 & 1 & -1 & -1 & 1 & -1 \\
-1 & 1 & 1 & -1 & -1 & 1
\end{array}\right) . \tag{2}
\end{align*}
$$

Similarly, the $\tilde{\boldsymbol{a}}_{i}$ are transformed by $\tilde{\tau}$ among themselves with the same matrix $\mathbf{M}$. Accordingly, we obtain

$$
\begin{equation*}
\mathbf{T}\left(\varepsilon_{1}, \varepsilon_{2}, \ldots, \varepsilon_{6}\right)=\left(\varepsilon_{1}, \varepsilon_{2}, \ldots, \varepsilon_{6}\right) \mathbf{M} \tag{3}
\end{equation*}
$$

where $\mathbf{T}=\operatorname{diag}(\tau, \tau, \tau, \tilde{\tau}, \tilde{\tau}, \tilde{\tau})$ is a diagonal matrix in 6 D . Since $\operatorname{det} \mathbf{T}=-1, \mathbf{T}$ represents a volume-conserving linear transformation of $E_{6} . T$ leaves $E_{3}$ and $\tilde{E}_{3}$ invariant. It acts as similarity transformations onto the two subspaces and, therefore, commutes with all the elements of $\mathrm{Y}_{h}^{\prime}$. $\tau$ satisfies $\tau^{3}=2 \tau+1$, so that we obtain $\mathrm{T}^{3}=2 \mathrm{~T}+\mathrm{E}$ and $\mathbf{M}^{3}=2 \mathbf{M}+\mathbf{E}$ with $\mathbf{E}$ being the 6 D unit matrix. It follows that $\mathbf{M}^{3}$ is a unimodular matrix and $\mathbf{T}^{3}$ induces an automorphism of $L_{\mathrm{P}} ; \mathbf{T}^{3} L_{\mathrm{P}}=L_{\mathrm{P}}$ (Elser 1985, Katz and Duneau 1986).
$L_{\mathrm{P}}$ has two sublattices with the hyperoctahedral point symmetry, namely, the face centred hypercubic lattice $L_{\mathrm{F}}$ and the body-centred lattice $L_{\mathrm{I}} ; L_{\mathrm{F}}=\left\{\left[n_{1} \ldots n_{6}\right] \mid n_{i} \in \boldsymbol{Z}\right.$ and $\left.n_{1}+\ldots n_{6} \equiv 0 \bmod 2\right\}$ and $L_{1}=\left\{\left[n_{1} \ldots n_{6}\right] \mid n_{i} \in \boldsymbol{Z}\right.$ and $n_{i}$ are either all even or all odd\}. Note that $L_{\mathrm{F}}$ (or $L_{1}$ ) is a superlattice of $L_{\mathrm{P}}$ such that the unit cell is doubled (or 32 pled). Note also that $L_{1}$ is a superlattice of $L_{\mathrm{F}}$. The three 6D lattices belong to different Bravais classes not only as hyperoctahedral lattices but also as 6D icosahedral lattices (Janssen 1986, Rokhsar et al 1987, Levitov and Rhyner 1988). The space groups of the three icosahedral lattices are $P \overline{5} \overline{3} m, F \overline{5} \overline{3} m$ and $I \overline{5} \overline{3} m$.

It is a matter of simple algebra to show the following. If $l=\left[n_{1} \ldots n_{6}\right] \in L_{\mathrm{F}}$ or $L_{1}$ then $\boldsymbol{l}^{\prime}=\mathbf{T} \boldsymbol{l}=\left[n_{1}^{\prime} \ldots n_{6}^{\prime}\right] \in L_{\mathrm{F}}$ or $L_{\mathrm{I}}$, respectively, so that $\mathbf{T}$ is an automorphism of $L_{\mathrm{F}}$ and $L_{1}$ (Rokhsar et al 1987, Levitov and Rhyner 1988).

We can now construct 3D icosahedral quasilattices from the 6D icosahedral lattices with the cut-and-projection method. A finite domain $S$ in $\tilde{E}_{3}$ is called starlike if $t S \subset S$ for $\forall t \in(0,1)$. A starlike domain is simply connected. Let $W$ be a starlike domain in $\tilde{E}_{3}$ and assume that it is invariant under $\tilde{\mathrm{Y}}_{h}$. Then the set of points in $E_{3}$ defined by.

$$
\begin{equation*}
Q_{\mathrm{P}}(\boldsymbol{\phi}, W)=\left\{\pi(\boldsymbol{l}) \mid \boldsymbol{l} \in L_{\mathrm{P}} \text { and } \tilde{\pi}(\boldsymbol{l}) \in \boldsymbol{\phi}+W\right\} \tag{4}
\end{equation*}
$$

is an icosahedral quasilattice, where $\phi \in \tilde{E}_{3}$ is an arbitrary vector, a so-called phase vector. $W$ is called a window. The local isomorphism class to which $Q_{\mathrm{P}}(\boldsymbol{\phi}, W)$ belongs is determined by $W$, but is independent of $\phi$. Therefore, we shall sometimes denote $Q_{\mathrm{P}}(\boldsymbol{\phi}, W)$ simply as $Q_{\mathrm{P}}(W) . Q_{\mathrm{P}}(W)$ has a macroscopic point symmetry represented by $\mathrm{Y}_{h}$. It has a selfsimilarity with ratio $\tau^{3} ; Q_{\mathrm{P}}\left(\tilde{\tau}^{3} W\right)$ is a sublattice (subset) of $Q_{\mathrm{P}}(W)$ (because $\tilde{\tau}^{3} W \subset W$ ) and is locally isomorphic to $\tau^{3} Q_{\mathrm{P}}(W)$ (Katz and Duneau 1986).

The projection of the Voronoi cell of $0 \in L_{\mathrm{P}}$ (the origin of $E_{6}$ ) onto $\tilde{E}_{3}$ is a rhombic triacontahedron $\mathscr{T} . Q_{\mathrm{P}}(\mathscr{T})$ is a 3D Penrose tiling with two kinds of rhombohedrons (Elser 1986, Katz and Duneau 1986).

Different icosahedral quasilattices $Q_{F}(\phi, W)$ and $Q_{1}(\phi, W)$ are constructed from $L_{\mathrm{F}}$ and $L_{\mathrm{I}}$ by equations similar to (4). They are sublattices of $Q_{\mathrm{P}}(\phi, W) . Q_{\mathrm{F}}\left(W^{\prime}\right)$ and $Q_{\mathrm{I}}\left(W^{\prime}\right)$ are never locally isomorphic to $Q_{\mathrm{P}}(W)$ however $W^{\prime}$ is chosen. $Q_{\mathrm{F}}(W)$ and $Q_{1}(W)$ are selfsimilar with respect to scaling with $\tau$.

## 3. A general theory of a classification of the special points of a Bravais lattice

Let $g$ be a $d$-dimensional space group and assume that it is symmorphic. Then, it is constructed as a semidirect product of a point group $G$ and a translational group, which is identified with a Bravais lattice (a $d$-dimensional $Z$-module) $L$. We shall denote this fact as $g=G * L$. We assume that $G$ includes the inversion operation $I$ : $I x=-\boldsymbol{x}$ for $\forall x \in E_{d}$.

Let $H$ be a subgroup of G. Then, we shall call $H$ a centring (sub-)group if the origin is the only fixed point of $E_{d}$ with respect to the action of $H$. The inversion operation $I$ has the origin as its only fixed point, so that a subgroup of $G$ (including itself) is a centring group if it includes $I$. Let H and $\mathrm{H}^{\prime}$ be subgroups of G such that $\mathrm{H} \subset \mathrm{H}^{\prime}$ and assume that H is a centring group. Then, so is $\mathrm{H}^{\prime}$.

The point group of $x \in E_{d}$ is defined by $\mathrm{G}(x)=\{\sigma \mid \sigma \in \mathrm{G}$ and $\sigma x \equiv \boldsymbol{x} \bmod L\}$. Obviously, $\mathrm{G}(\boldsymbol{x})=\mathrm{G}(\boldsymbol{x}+\boldsymbol{l})$ for $\forall l \in L . \mathrm{G}(\boldsymbol{x})$ is nothing but the isotropy group of $\boldsymbol{x}$ with respect to the action of $G$ onto the torus, $T^{d}=E_{d} / L\left(\simeq \mathbb{R}^{d} / \mathbb{Z}^{d}\right)$.
$\boldsymbol{x} \in E_{d}$ is called a special point of $L$ if $\mathrm{G}(\boldsymbol{x})$ is a centring group. Let $\boldsymbol{x}_{0}$ be a special point (of $L$ ). Then, the set of all the translationally equivalent special points to $x_{0}$ is given by $L\left(x_{0}\right)=x_{0}+L\left(=\left\{x_{0}+\boldsymbol{l} \mid \boldsymbol{l} \in L\right\}\right)$, so that special points can be considered in modulo $L$.

If $x_{0} \in E_{d}$ is a special point of $L$, we obtain that $\mathrm{G}\left(\sigma x_{0}\right)=\sigma \mathrm{G}\left(x_{0}\right) \sigma^{-1} \simeq \mathrm{G}\left(x_{0}\right)$. Therefore, $\sigma x_{0}$ is an equivalent special point to $x_{0}$ with respect to the space group $\mathscr{G}$. The total number of equivalent special points (modulo $L$ ) to $\boldsymbol{x}_{0}$ is given by $|\mathrm{G}| /\left|\mathrm{G}\left(\boldsymbol{x}_{0}\right)\right|$, which we shall call the order of $\boldsymbol{x}_{0}$. It is obvious that every special point of $L$ is an isolated point, so that the set of all the special points of $L$ is a discrete set in $E_{d}$ and the number of different special points (modulo $L$ ) is finite.

A sublattice $L^{\prime}$ of $L$ is called a G-superlattice of $L$ if $L^{\prime}$ is a Bravais lattice and its point group includes $G$. For example, $L_{\mathrm{F}}$ is a $\mathrm{Y}_{h}^{\prime}$-superlattice of $L_{\mathrm{P}}$. Let $q$ be the number of lattice points of $L$ in a unit cell of $L^{\prime}$. Then, $L$ is divided into $q$ sublattices which are translationally equivalent to $L^{\prime}$.

Let $L^{\prime}$ be a G-superlattice of $L$. Then, $\mathrm{G}^{\prime}(x) \equiv\left\{\sigma \mid \sigma \in \mathrm{G}\right.$ and $\left.\sigma x \equiv x \bmod L^{\prime}\right\} \subset \mathrm{G}(x)$. Therefore, a special point of $L^{\prime}$ is always a special point of $L$ but the converse is not necessarily true. If we know all the special points of $L$, all the special points of $L^{\prime}$ are obtained from those by examining whether they are actually so.

Let $\mathrm{G}^{\prime}$ be a subgroup of G . Then, $\mathrm{G}^{\prime}(x)=\left\{\sigma \mid \sigma \in \mathrm{G}^{\prime}\right.$ and $\left.\sigma x \equiv x \bmod L\right\} \subset \mathrm{G}(x)$, $\forall x \in E_{d}$. Therefore, a special point of $L$ with respect to the space group $g^{\prime}=\mathrm{G}^{\prime} * L$ is also a special point of $L$ with respect to $g$, but the converse is not always true. All the special points of $L$ with respect to $g^{\prime}$ are obtained from those with respect to $g$ by examining them. Note, however, that two equivalent special points with respect to $g$ are not necessarily equivalent with respect to $g^{\prime}$.

The special points of $L$ are divided into type I or II according to whether the relevant point groups include the inversion operation or not, respectively. The condition that $I x \equiv x \bmod L x \in E_{d}$ is equivalent to $2 x \equiv 0 \bmod L$. Therefore, the set of all the type-I special points of $L$ coincides with the half lattice, $L^{(\mathrm{H})}=L / 2(=\{\boldsymbol{l} / 2 \mid \boldsymbol{l} \in L\})$. The number of the lattice points of $L^{(H)}$ in a unit cell of $L$ is equal to $2^{d}$.

The origin of $E_{d}$ is a type-I special point of $L$ because $\mathrm{G}(0)=\mathrm{G}$. Therefore, $L$ $(=L(0))$ is a trivial but important set of equivalent special points of $L$. We shall denote this class of special points by $\Gamma$, following the convention in the band-structure theory of solids.

We consider here a special case where there exists a special point $x_{0}$ such that $\mathrm{G}\left(\boldsymbol{x}_{0}\right)=\mathrm{G}$ but $x_{0} \notin L$ (for example, this is the case for the simple cubic lattice). Then, we can show easily that $\mathrm{G}(\boldsymbol{x})=\mathrm{G}\left(\boldsymbol{x}_{0}+\boldsymbol{x}\right) \forall \boldsymbol{x} \in E_{d}$. Therefore, all the special points (modulo $L$ ) are grouped into pairs such that each pair of special points have a common point symmetry and their separation is equal to $x_{0}$ in modulo $L$. It is usual that $2 x_{0} \equiv 0 \bmod L$, so that the relationship between the members of each pair is symmetric.

All the lattice points of $L^{(\mathrm{H})}$ are special points of $L$ as noted previously and, moreover, $L$ is a G-superlattice of $L^{(H)}$. There can exist other Bravais lattices having similar properties. It can be shown generally that there exists a Bravais lattice $K$ such that $K$ includes all the special points of $L$ and, moreover, $L$ is a G-superlattice of $K$.
$E_{d}$ is divided into Voronoi cells of the lattice points of $L$; the cells are translationally congruent with the one centred at the origin, which we shall denote as $V_{0} . V_{0}$ is a polytope whose point symmetry is equal to $G$. A member of a translationally equivalent
set of special points is included in $V_{0}$. All the special points but the $\Gamma$ point included in $V_{0}$ are located on the boundary. Some of them coincide with the vertices of $V_{0}$. Others may coincide with the middle points of the edges, the centres of the 2 D surfaces etc. In particular, the centre of a $(d-1)$-dimensional surface of $V_{0}$ is a type-I special point, which is equal to half a lattice vector of $L$; the surface bisects the lattice vector perpendicularly.

## 4. The special points of icosahedral lattices in 6 D

In this section we shall identify $\mathrm{Y}_{h}^{\prime}$ with $\mathrm{Y}_{h}$, so that we shall denote subgroups of $\mathrm{Y}_{h}^{\prime}$ by the symbols, $\mathrm{D}_{5 d}, \mathrm{D}_{2 h}$, etc, which represent 3 D point groups.

### 4.1. The case of $P \overline{5} \overline{3} m$

The type-I special points of $L_{\mathrm{P}}$ are the lattice points of its half lattice $L_{\mathrm{P}}^{(\mathrm{H})}$ and there are 64 different points modulo $L_{\mathrm{P}}$. They are classified in I as listed in part ( $a$ ) of table 1. The representative $x_{0}$ of each class of special points is so chosen that the projection of the main axis of $\mathrm{G}\left(\boldsymbol{x}_{0}\right)$ onto $E_{3}$ is parallel to [ $\left.\tau 10\right]\left(=a_{1}\right)$, [111] or [100] according as $\mathrm{G}\left(x_{0}\right)$ is isomorphic to $\mathrm{D}_{5 d}, \mathrm{D}_{3 d}$ or $\mathrm{D}_{2 h}$, respectively.

Since $G(x(R))=Y_{h}$ with $x(R)=[111111] / 2$, a pair of special points, $x_{0}$ and $x(R)-$ $x_{0}$, have a common point symmetry. $X_{3}$ and $M_{3}$ would be equivalent to each other if $\Omega(6)$ were taken to be the point group of $L_{\mathrm{p}}$.

Table 1. The special points of the 6 D icosahedral lattices. The first row in each table lists symbols assigned to different classes of special points. The number suffixed to a symbol represents the order of the rotation whose axis coincides with the main axis of the point symmetry. The third row lists the number of different special points belonging to each class in a unit cell of the relevant lattice. The fourth row lists a representative of each class of special points.

|  | (a) $P \overline{53} m$ |  |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| symbol | $\Gamma$ | $X_{5}$ | $X_{2}$ | $X_{3}$ | $M_{3}$ | $M_{2}$ | $M_{5}$ | $R$ |
| point symmetry | $\mathrm{Y}_{h}$ | $\mathrm{D}_{5 d}$ | $\mathrm{D}_{2 h}$ | $\mathrm{D}_{3 d}$ | $\mathrm{D}_{3 d}$ | $\mathrm{D}_{2 h}$ | $\mathrm{D}_{5 d}$ | $\mathrm{Y}_{h}$ |
| order | 1 | 6 | 15 | 10 | 10 | 15 | 6 | 1 |
| representative | $[000000]$ | $\left[\frac{1}{2} 00000\right]$ | $\left[\frac{1}{2} 00 \frac{1}{2} 00\right]$ | $\left[\frac{11}{2} \frac{1}{2} 000\right]$ | $\left[000 \frac{1}{2} \frac{1}{2}\right]$ | $\left[0 \frac{1}{2} \frac{1}{2} 0 \frac{1}{2} \frac{1}{2}\right]$ | $\left[0 \frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2}\right]$ | $\left[\frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2}\right]$ |

(b) $F \overline{5} \overline{3} m$

| symbol | $\Gamma$ | $H$ | $N$ | $N^{\prime}$ | $M$ | $M^{\prime}$ | $P$ | $P^{\prime}$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| point symmetry | $\mathrm{Y}_{h}$ | $\mathrm{Y}_{h}$ | $\mathrm{D}_{2 h}$ | $\mathrm{D}_{2 h}$ | $\mathrm{D}_{2 h}$ | $\mathrm{D}_{2 h}$ | $\mathrm{Y}_{h}$ | $\mathrm{Y}_{h}$ |
| order | 1 | 1 | 15 | 15 | 15 | 15 | 1 | 1 |
| representative | $[000000]$ | $[100000]$ | $\left[\frac{1}{2} 00 \frac{\overline{1}}{2} 00\right]$ | $\left[0 \frac{1}{2} 00 \frac{1}{2} 0\right]$ | $\left[\frac{1}{2} 0 \frac{1}{2} \frac{1}{2} 0\right]$ | $\left[0 \frac{1}{2} 0 \frac{\overline{1}}{2} \frac{1}{2}\right]$ | $\left[\frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{\overline{1}}{2}\right]$ | $\left[\frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2}\right]$ |

(c) $I \overline{5} \overline{3} \mathrm{~m}$

| symbol | $\Gamma$ | $X_{5}$ | $X_{2}$ | $X_{3}$ | $L_{3}$ | $L_{3}^{\prime}$ | $L_{5}$ | $L_{s}^{\prime}$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| point symmetry | $\mathrm{Y}_{h}$ | $\mathrm{D}_{5 d}$ | $\mathrm{D}_{2 h}$ | $\mathrm{D}_{3 d}$ | $\mathrm{D}_{3 d}$ | $\mathrm{D}_{3 d}$ | $\mathrm{D}_{5 d}$ | $\mathrm{D}_{s d}$ |
| order | 1 | 6 | 15 | 10 | 10 | 10 | 6 | 6 |
| representative | $[000000]$ | $[1000000][100100]$ | $[111000]$ | $\left[\frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2}\right]$ | $\left[\frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2}\right]$ | $\left[\frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2}\right]$ | $\left[\frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2}\right]$ |  |

We have mentioned in I, without any proof, that $L_{\mathrm{P}}$ has no type-II special points. We present here a proof of it. Of the centring subgroups of $\mathrm{Y}_{h}$, only $\mathrm{T}, \mathrm{D}_{5}, \mathrm{D}_{3}$ and $D_{2}$ do not include the inversion operation. Since $T$ includes $D_{2}$ as its subgroup, the proposition under consideration is true if we can prove the following lemma.

Lemma. Let $x_{0}$ be a special point of $L$ and assume that $\mathrm{H} \subset \mathrm{G}\left(\boldsymbol{x}_{0}\right)$ with $\mathrm{H}=\mathrm{D}_{5}, \mathrm{D}_{3}$ or $\mathrm{D}_{2}$. Then, $x_{0} \in L_{\mathrm{P}}^{(\mathrm{H})}$.

Proof. $\mathrm{D}_{5}, \mathrm{D}_{3}$ and $\mathrm{D}_{2}$ have ten, six and three twofold rotations respectively. Let H be one of the three point groups and assume that one of the basis vectors of $L_{P}$, say $\varepsilon_{i}$, is given. Then, there exists a twofold rotation $\sigma$ of H such that $\sigma \varepsilon_{i}=-\boldsymbol{\varepsilon}_{i}$. This statement can be confirmed by examining each case separately. Now, let $\boldsymbol{x}_{0}=$ [ $h_{1} h_{2} \ldots h_{6}$ ] be a special point such that $\mathrm{G}\left(\boldsymbol{x}_{0}\right) \supset \mathrm{H}$. Then, we can conclude that $2 h_{i} \equiv 0 \bmod \boldsymbol{Z}$ for all $i$ and, consequently, $\boldsymbol{x}_{0} \in L_{\mathrm{P}}^{(\mathrm{H})}$.
$V_{0}^{(\mathrm{P})}$, the Voronoi cell of the origin of $L_{\mathrm{P}}$, is a 6D hypercube whose 64 vertices are [ $h_{1} h_{2} \ldots h_{6}$ ] where $h_{i}$ takes the values $\pm \frac{1}{2}$. That is, the vertices belong to class $R$ of the special points of $L_{P}$. More generally, a special point is located on the centre of a $k$-dimensional surface (a hypercube) of $V_{0}^{(\mathrm{P})}$ if the number of zeros in the indices of the point is $k$.

### 4.2. The case of $\overline{5} \overline{3} m$

The 64 type-I special points of $L_{\mathrm{F}}$ are classified as listed in part (b) of table 1. The symbols denoting different special points are chosen in analogy to the case of the face centred cubic lattice. $\Gamma$ and $H$ form $L_{\mathrm{P}} ; L_{\mathrm{P}}=L_{\mathrm{F}} \cup\left(\boldsymbol{x}(H)+L_{\mathrm{F}}\right)$ with $\boldsymbol{x}(H)=[100000]$. $P$ and $P^{\prime}$ are located on the body centres of the lattice $L_{\mathrm{P}}$, so that $\Gamma, H, P$ and $P^{\prime}$ form a 6 D body centred hypercubic lattice $L_{\mathrm{P}} \cup\left(\boldsymbol{x}(P)+L_{\mathrm{P}}\right)$, which is nothing but $L_{\mathrm{I}}^{(\mathrm{H})}$. This result is consistent with the general result on the relationship between the special points of two lattices $L$ and $L^{\prime}$ satisfying $L \subset L^{\prime}$.
$V_{0}^{(\mathrm{F})}$ is a 6 D polytope with 76 vertices. Twelve of them belong to $H$ and the remaining 64 to $P$ and $P^{\prime}$. A 5D surface of $V_{0}^{(\mathrm{F})}$ is a polytope with 18 vertices; two of them belong to $H$ and the remaining sixteen to $P$ and $P^{\prime} . V_{0}^{(\mathrm{F})}$ has 60 equivalent iD surfaces whose centres belong to $N$ and $N^{\prime}$.

We will consider here whether $L_{\mathrm{F}}$ has any type-II special point. Since $L_{\mathrm{F}} \subset L_{\mathrm{P}}$, special points of $L_{\mathrm{F}}$ are those of $L_{\mathrm{P}}$. The type-I special points of $L_{\mathrm{F}}$ are, indeed, special points of $L_{\mathrm{P}}$. The point symmetries of other special points of $L_{\mathrm{P}}$ are $\mathrm{D}_{5 d}$ and $\mathrm{D}_{3 d}$, whose centring subgroups without the inversion operation are $\mathrm{D}_{5}$ and $\mathrm{D}_{3}$, respectively. Let $x_{0}$ be a special point of $L_{\mathrm{P}}$ and assume that it belongs to, say, $X_{5}$. Then, it is shown easily that $\sigma x_{0}-x_{0}$ is indexed with six integers which sum to an odd integer, where $\sigma$ is any twofold rotation in $\mathrm{G}\left(\boldsymbol{x}_{0}\right)\left(\simeq \mathrm{D}_{5}\right)$. Therefore, $\boldsymbol{x}_{0}$ cannot be a special point of $L_{\mathrm{F}}$. By similar arguments, we can show that $M_{5}, X_{3}$ and $M_{3}$ of $L_{\mathrm{P}}$ cannot be type-II special points of $L_{F}$.

### 4.3. The case of $1 \overline{5} \overline{3} m$

Since $\quad L_{\mathrm{I}}=\left(2 L_{\mathrm{P}}\right) \cup\left([111111]+2 L_{\mathrm{P}}\right)$, we obtain $L_{\mathrm{I}}^{(\mathrm{H})}=L_{\mathrm{P}} \cup L_{\mathrm{P}}^{\prime}$ with $L_{\mathrm{P}}^{\prime}=$ [111111]/2 $+L_{P}$. Therefore, 32 type-I special points of $L_{1}$ form $L_{P}$ and have indices with integers only. On the other hand, the remaining 32 type-I special points have
indices with half-integers only. The former (or latter) 32 special points are classified into four classes as presented in the first (or last) four columns in part (c) of table 1. The last four classes would be equivalent if $\Omega(6)$ were taken to be the point group of $L_{1}$.
$\Gamma$ and fifteen $X_{2}$ of $L_{1}$ form $L_{F}$, which is a $\mathrm{Y}_{h}$-superlattice of $L_{\mathrm{p}}$.
Since $L_{1} \subset L_{\mathrm{F}}$, special points of $L_{1}$ are obtained from those of $L_{\mathrm{F}}$. The question here is whether the special points $N, N^{\prime}, M$ and $M^{\prime}$ in part ( $b$ ) of table 1 are type-II special points of $L_{1}$. If the answer is affirmative the relevant point symmetry is $D_{2}$ $\left(\subset \mathrm{D}_{2 h}\right.$ ). Let us assume that $x_{0} \in E_{6}$ belongs to, say, $N$ in part (b) of table 1. Then, we can show easily that $\sigma x_{0}-x_{0}$ with $\sigma \in \mathrm{D}_{2}$ is indexed with integers including both even and odd ones. Therefore, $\boldsymbol{x}_{0}$ is not a special point of $L_{1}$. By similar arguments, we can conclude that $L_{1}$ have no type-II special points.
$V_{0}^{(1)}$ is a 6D polytope with 160 vertices and 76 5D surfaces. The vertices belong to $X_{3}$. The centres of twelve 5D hypersurfaces belong to $X_{5}$ and the remaining 64 to $L_{3}$, $L_{3}^{\prime}, L_{5}$ and $L_{5}^{\prime}$.

## 5. Discussions

The 4D decagonal and dodecagonal lattices investigated in Niizeki (1989b) have type-II special points. Furthermore, the $P$ - (or $W$-) point of the face- (or body-) centred cubic lattice is also a type-II special point. Therefore, the present results that the three icosahedral lattices have no type-II special points are by no means obvious a priori, and we have presented proofs of them.

Let $L$ be one of the three icosahedral lattices $L_{\mathrm{P}}, L_{\mathrm{F}}$ and $L_{1}$ and let $Q(W)$ be the icosahedral quasilattice obtained from $L$ with window $W$. Then, $Q(W)$ is a discrete subset of $\pi(L)$, which is a dense set in $E_{3}$. Let $L[X]$ be the set of all the special points of $L$ belonging to class $X$. Then, $\pi(L[X])$ is also a dense set. If a discrete subset of $\pi(L[X])$ is chosen appropriately, each point of the set represents the centre of a common local structure of $Q(W)$ with point symmetry $G(X)$ (Niizeki 1989b).

For example, the body centre of a rhombohedron in 3D Penrose tiling $Q_{\mathrm{P}}(\mathscr{T})$ belongs to $\pi\left(L_{\mathrm{P}}\left[X_{3}\right]\right)$ or $\pi\left(L_{\mathrm{P}}\left[M_{3}\right]\right)$ depending on whether the rhombohedral angle is acute or obtuse, respectively. Similarly, the centre of a face of a rhombohedron belongs to $\pi\left(L_{\mathrm{P}}\left[\mathrm{X}_{2}\right]\right) . Q_{\mathrm{p}}(\mathscr{T})$ has the local structures of a rhombic icosahedron composed of two prolate rhombohedra and two oblate ones (Elser and Henley 1985, Henley 1986). It can be shown that their body centres belong to $\pi\left(L_{\mathrm{P}}\left[M_{2}\right]\right)$. Note, however, that the configuration of the interior of every rhombic icosahedron breaks the point symmetry $D_{2 h}$ (Henley 1986). We may call it a spontaneous symmetry breaking (Niizeki 1989b). We will not mention here the local structures associated with other special points of $L_{\mathrm{P}}$.

I have not investigated yet local structures of $Q_{\mathrm{F}}(W)$ nor $Q_{1}(W)$ for any $W$. The case where $W=\tilde{\pi}\left(V_{0}\right)$ with $V_{0}$ being the Voronoi cell of the origin will be promising; $\tilde{\pi}\left(V_{0}^{(\mathrm{F})}\right)$ as well as $\tilde{\pi}\left(V_{0}^{(\mathrm{P})}\right)$ is a rhombic triacontahedron, while $\tilde{\pi}\left(V_{0}^{(\mathrm{I})}\right)$ is a regular dodecahedron. This subject awaits our intensive investigation.

Every icosahedral quasilattice has a selfsimilarity with ratio $\tau$ or $\tau^{3}$. The local structures may change on the selfsimilarity transformation though their point symmetries cannot (Niizeki 1989b). This is because different classes of special points of $L$ form a multiplet such that its members are permuted cyclically among themselves by the automorphism induced by $M$ (or $M^{3}$ for the case of $L_{P}$ ). It is a matter of
elementary algebra to find such a multiplet, so we present only the results. $\Gamma$ is always a singlet. Other singlets are $X_{2}, M_{2}$ and $R$ of $L_{\mathrm{P}}, M^{\prime}$ of $L_{\mathrm{F}}$ and $X_{2}$ of $L_{1}$. $L_{\mathrm{P}}$ has two doublets $\left\{X_{5}, M_{5}\right\}$ and $\left\{X_{3}, M_{3}\right\}$. $L_{\mathrm{F}}$ has two triplets $\left\{H, P, P^{\prime}\right\}$ and $\left\{N, N^{\prime}, M\right\} . L_{1}$ has also two triplets $\left\{X_{5}, L_{5}, L_{5}^{\prime}\right\}$ and $\left\{X_{3}, L_{3}, L_{3}^{\prime}\right\}$. $L_{\mathrm{P}}$ has no higher multiplets than the doublets because $\left(M^{3}\right)^{2}=8 M+5 E \equiv E \bmod 2$. On the other hand, $M^{3}=2 M+E \equiv$ $J+E \bmod 2$, with $J={ }^{\mathrm{t}} u u$ where $u=(1,1,1,1,1,1)$ is a row vector. Therefore, $L_{\mathrm{F}}$ and $L_{1}$ can have triplets because $n_{1}+n_{2}+\ldots+n_{6} \equiv 0 \bmod 2$ for $\left[n_{1} n_{2} \ldots n_{6}\right] \in L_{\mathrm{F}}$ (or $L_{1}$ ).

The reciprocal lattice of $L_{\mathrm{P}}$ is given by $L_{\mathrm{P}}^{*}=\left.L_{\mathrm{P}}\right|_{a \rightarrow a^{*}}$ with $a^{*}=2 \pi / a$, while those of $L_{\mathrm{F}}$ and $L_{\mathrm{I}}$ are by $L_{\mathrm{F}}^{*}=\left.L_{\mathrm{I}}\right|_{a \rightarrow a^{*}}$ and $L_{1}^{*}=\left.L_{\mathrm{F}}\right|_{a \rightarrow a^{*}}$ with $a^{*}=\pi / a$. The relevant Voronoi cell $V_{0}^{*}$ of each reciprocal lattice is the first Brillouin zone and the special points are high-symmetry points in the zone. On the other hand, the special points (wavevectors) in the reciprocal space of an icosahedral quasilattice are given by the projections of the special points of $L_{X}^{*}$ with $X=\mathrm{P}, \mathrm{F}$ or I onto the 3 D reciprocal space $E_{3}^{*}$. They form a dense set in the reciprocal space. However, the set is practically discrete because special points belonging to a single class have different intensities which are determined by the Fourier components of the window function with respect to the conjugate wavevectors (see I). Further details of this subject will be discussed elsewhere.

Let the 6 D space group $g^{\prime}$ be a subgroup of $g=\mathrm{Y}_{h} * L_{X}$ with $X=\mathrm{P}, \mathrm{F}$ or I. Then, special points defined with respect to $g^{\prime}$ are always special points of $L_{X}$ with respect to $g$. Therefore, the former special points are all obtained from the latter by examining them. Accordingly, the present results will be the basis of the investigation of special points of other icosahedral lattices including the case of a non-symmorphic space group (Janssen 1986, Rokhsar et al 1988, Levitov and Rhyner 1988).

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Note added in proof. Let $C$ be a class of special points of an icosahedral lattice $L_{X}$ with $X=\mathrm{P}, \mathrm{F}$ or I . Then, the local structure associated with a special point of $Q_{X}(W)$ with $W=\tilde{\pi}\left(V_{0}^{(X)}\right)$ is a translate of $\pi\left(\left(x_{0}+L_{X}\right) \cap V_{0}^{(X)}\right)$ with $x_{0} \in L_{X}[C]$.

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